Module 6: Operational Modal Analysis

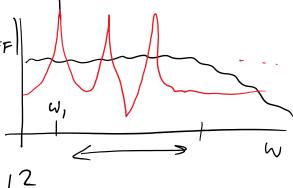
Monday, October 19, 2020

$$S_{\times\times}$$
 = E($\times\times^*$)

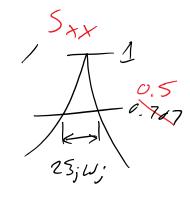
$$S_{xx} = E(HFH^*F^*)$$

$$X = FFT(x)$$

$$S_{\times X} = |H|^2 S_{FF}$$



L LOOKS 11he 1/W) /2



SFF(W) = const

1.) Peak - picking
2.) Italf-power BW -> § (O.

$$|H(w)|^2 = \left|\frac{(1/m)}{W_n^2 - w^2 + iw 25w_n}\right|^2 W$$

$$(0.707 \rightarrow 0.5)$$

$$W = \omega_n$$

3.) Mode Shapes

$$\begin{cases}
S_{\times_{1}\times,} \\
S_{\times_{2}\times_{1}} \\
S_{\times_{3}\times,}
\end{cases} = E \begin{pmatrix}
H_{1p} F_{p} H_{1p}^{*} F_{p}^{*} \\
H_{2p} F_{p} H_{1p}^{*} F_{p}^{*}
\end{pmatrix}$$

$$H_{1p} = \sum_{r=1}^{N} \frac{p_{1r} p_{pr}}{w_{r}^{2} - w_{1}^{2} + w_{2}^{2} + w_{2}^{2}}$$

$$Y = Mode #$$

 $= \{H(:, p)\} = \{F_p F_p^*\} H_{1p}^*$

$$-(\Pi(\cdot,r)) \sqsubseteq (IPP)$$

$$\propto H(:,p) \text{ weas } pts[1,2,3...N_m]$$

$$= \left(\frac{1}{r} \frac{1603r \text{ Spr}}{w_r^2 - w^2 + iw25rwr}\right) SF_pF_p\left(\frac{1}{r} \frac{1}{2} \frac{1$$

$$\begin{cases}
S_{x_1x_1} \\ S_{x_2x_1} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
\begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}
\end{cases} = \begin{cases}
S_{x_1} \\ S_{x_2} \\ \vdots \\ S_{x_2x_1}$$

ref. sensor