## Lecture 3f - How are FRFs Measured?

Thursday, October 8, 2020 6:50 PM

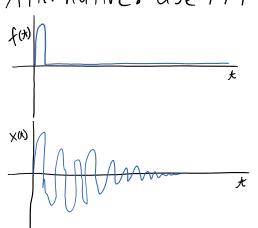
$$f(x) = Re(Fe^{i\omega x}) \longrightarrow x(x) = Re(Xe^{i\omega x})$$
  
 $X = HF \longrightarrow H(\omega) = \frac{X(\omega)}{F(\omega)}$ 

1.) apply f(t) above
2.) Wait for steady-state
3.) Measure complex amplitudes F, X
4.) H = X/F

-> This method is great but can be very slow!  $\mathcal{T} = \frac{1}{8 \omega_n} \rightarrow \mathcal{T} = \frac{1}{0.01 \cdot (1 \, \text{Hz} \cdot 2\pi)} \stackrel{\frown}{=} 16 \text{ sec}$ 

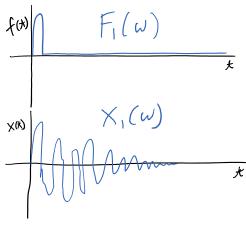
82 > 2 min per frequency

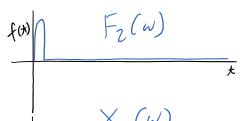
Alternative: Use FFT

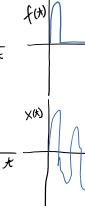


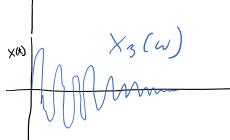
FFT gives  $F(\omega)$ ,  $X(\omega)$ for frequencies  $[0, \omega_1, 2\omega_1, ... \omega_{max}]$  $H(\omega) = \frac{X(\omega)}{F(\omega)}$ 

Average over several measurements to minimize noise!









$$\begin{array}{lll} X_{1}(\omega) &=& H(\omega) \; F_{1}(\omega) \\ X_{2}(\omega) &=& H(\omega) \; F_{2}(\omega) \\ X_{3}(\omega) &=& H(\omega) \; F_{3}(\omega) \end{array} = \begin{bmatrix} X_{1} \\ X_{2} \\ X_{3} \end{bmatrix} = \begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} H \quad \text{at each fing. (a)}$$

"H<sub>1</sub>" Solution
$$\begin{bmatrix} F_{1}^{*}F_{2}^{*}F_{3}^{*} \end{bmatrix} \begin{bmatrix} X_{1} \\ X_{2} \\ X_{3} \end{bmatrix} = \begin{bmatrix} F_{1}^{*}F_{2}^{*}F_{3}^{*} \end{bmatrix} \begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} H$$

$$\begin{bmatrix} X_{1}^{*}X_{2}^{*}X_{3}^{*} \end{bmatrix} \begin{bmatrix} X_{1} \\ X_{2} \\ X_{3} \end{bmatrix} = \begin{bmatrix} X_{1}^{*}X_{2}^{*}X_{3}^{*} \end{bmatrix} \begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} H$$

$$\begin{bmatrix} F_{1}^{*}X_{1} + F_{2}^{*}X_{2} + F_{3}^{*}X_{3} \end{bmatrix} = \begin{bmatrix} X_{1}^{*}X_{2}^{*}X_{3}^{*}X_{3}^{*} \end{bmatrix} \begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} H$$

$$\begin{bmatrix} F_{1}^{*}X_{1} + F_{2}^{*}X_{2} + F_{3}^{*}X_{3} \end{bmatrix} = \begin{bmatrix} X_{1}^{*}X_{2}^{*}X_{3}^{*}X_{3}^{*} \end{bmatrix} \begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} H$$

$$\begin{bmatrix} F_{2}^{*}X_{1} + F_{3}^{*}X_{2} + F_{3}^{*}X_{3} \end{bmatrix} = \begin{bmatrix} X_{1}^{*}X_{2}^{*}X_{3}^{*}X_{3}^{*} \end{bmatrix} \begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} H$$

$$\begin{bmatrix} F_{2}^{*}X_{1} + F_{3}^{*}X_{2} + F_{3}^{*}X_{3}^{*}X_{3}^{*} \end{bmatrix} \begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} H$$

$$(F_{1}^{*}X_{1} + F_{2}^{*}X_{2} + F_{3}^{*}X_{3}) = \sum_{j=1}^{2} F_{j}^{*}X_{j}$$

$$S_{XF} = \frac{1}{N} \sum_{j=1}^{N} X_{j}F_{j}^{*}$$

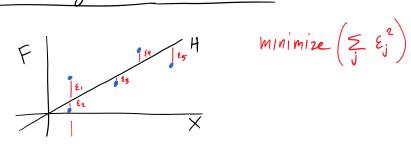
$$S_{XF} = S_{FF}H$$

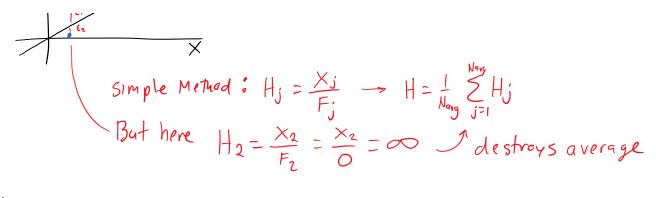
$$H_{\perp}(\omega_{K}) = S_{FX}(\omega)S_{FF}(\omega_{K})$$

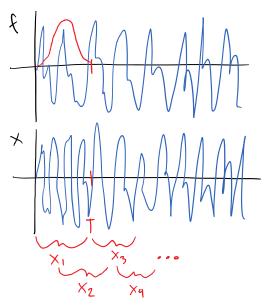
$$\begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} + \begin{bmatrix} X_{1}^{*} \times X_{2}^{*} \times X_{3}^{*} \end{bmatrix} \begin{bmatrix} X_{1} \\ X_{2} \\ X_{3} \end{bmatrix} = \begin{bmatrix} X_{1}^{*} \times X_{2}^{*} \times X_{3}^{*} \end{bmatrix} \begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} + \begin{bmatrix} X_{1}^{*} \times X_{2}^{*} \times X_{3}^{*} \end{bmatrix} \begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} + \begin{bmatrix} X_{1}^{*} \times X_{2}^{*} \times X_{3}^{*} \end{bmatrix} \begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} + \begin{bmatrix} X_{1}^{*} \times X_{2}^{*} \times X_{3}^{*} \end{bmatrix} \begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} + \begin{bmatrix} X_{1}^{*} \times X_{2}^{*} \times X_{3}^{*} \end{bmatrix} \begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} + \begin{bmatrix} X_{1}^{*} \times X_{2}^{*} \times X_{3}^{*} \end{bmatrix} \begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} + \begin{bmatrix} X_{1}^{*} \times X_{2}^{*} \times X_{3}^{*} \end{bmatrix} \begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} + \begin{bmatrix} X_{1}^{*} \times X_{2}^{*} \times X_{3}^{*} \end{bmatrix} \begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} + \begin{bmatrix} X_{1}^{*} \times X_{2}^{*} \times X_{3}^{*} \end{bmatrix} \begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} + \begin{bmatrix} X_{1}^{*} \times X_{2}^{*} \times X_{3}^{*} \end{bmatrix} \begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} + \begin{bmatrix} X_{1}^{*} \times X_{2}^{*} \times X_{3}^{*} \end{bmatrix} \begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} + \begin{bmatrix} X_{1}^{*} \times X_{2}^{*} \times X_{3}^{*} \end{bmatrix} \begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} + \begin{bmatrix} X_{1}^{*} \times X_{2}^{*} \times X_{3}^{*} \end{bmatrix} \begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} + \begin{bmatrix} X_{1}^{*} \times X_{2}^{*} \times X_{3}^{*} \end{bmatrix} \begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} + \begin{bmatrix} X_{1}^{*} \times X_{2}^{*} \times X_{3}^{*} \end{bmatrix} \begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} + \begin{bmatrix} X_{1}^{*} \times X_{2}^{*} \times X_{3}^{*} \end{bmatrix} \begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} + \begin{bmatrix} X_{1}^{*} \times X_{2}^{*} \times X_{3}^{*} \end{bmatrix} \begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} + \begin{bmatrix} X_{1}^{*} \times X_{2}^{*} \times X_{3}^{*} \end{bmatrix} \begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} + \begin{bmatrix} X_{1}^{*} \times X_{2}^{*} \times X_{3}^{*} \end{bmatrix} \begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} + \begin{bmatrix} X_{1}^{*} \times X_{2}^{*} \times X_{3}^{*} \end{bmatrix} \begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \end{bmatrix} + \begin{bmatrix} X_{1}^{*} \times X_{2}^{*} \times X_{3}^{*} \end{bmatrix} \begin{bmatrix} X_{1} \\ Y_{2} \\ Y_{3} \end{bmatrix} \begin{bmatrix} X_{1} \\ Y_{2} \end{bmatrix} \begin{bmatrix} X_{1} \\ Y_{2}$$

These formulas are also valid for a MIMO test

Least Squares Solution







Apply window to minimize leakage:

Hanning Window:  $W(k) = \left(1 - \left(05\left(\frac{W_1 t}{2}\right)\right)^2$ 

W(x) -> W(W)

Distartion typically minimal