

$$\{\phi\}_1^T [M] \{\phi\}_1 = \mu_1, \quad \{\phi\}_1 = \frac{\{\phi\}_1}{\sqrt{\mu_1}} \quad (2)$$

$$[\Phi] = [\{\phi\}_1 \{\phi\}_2 \dots]$$

$$\{x\} = [\Phi] \{\eta\} \rightarrow \text{plug in to EOM}$$

$$[M][\Phi]\{\ddot{\eta}\} + [C][\Phi]\{\dot{\eta}\} + [K][\Phi]\{\eta\} = \{F\}$$

pre-mult by $[\Phi]^T$

$$\{\ddot{\eta}\} + [\Phi]^T [C] [\Phi] \{\dot{\eta}\} + [\omega_n^2] \{\eta\} = [\Phi]^T \{F\}$$

if some assumptions about $[C]$ are met

$$[\Phi]^T [C] [\Phi] = \begin{bmatrix} 2\underline{\zeta_1 \omega_1} & 0 & 0 \\ 0 & 2\underline{\zeta_2 \omega_2} & 0 \\ 0 & 0 & \dots \end{bmatrix}$$

$$\ddot{\eta}_1 + 2\underline{\zeta_1 \omega_1} \dot{\eta}_1 + \omega_1^2 \eta_1 = \{\phi\}_1^T \{F\} \quad \text{only } \eta_1$$

$$\ddot{\eta}_2 + 2\underline{\zeta_2 \omega_2} \dot{\eta}_2 + \omega_2^2 \eta_2 = \{\phi\}_2^T \{F\}$$

$\vdots$

modal eq. of motion
for the r th mode

Force applies to all
modes

SDOF system

2nd
gen. sol

$$\eta_r(t) = \text{Re}(A_r e^{\lambda_r t})$$

$$\eta_1(t), \eta_2(t), \dots$$

$$\lambda_r = -\zeta_r \omega_r \pm i \omega_{dr}$$

$$\omega_{dr} = \omega_r \sqrt{1 - \zeta_r^2}$$

$$\{x\} = [\Phi] \begin{bmatrix} \eta_1(t) \\ \eta_2(t) \\ \vdots \end{bmatrix}$$

"Mod 2. MDOF - Free Resp Ex. m"

physical
coord.

resp. in modal coord

~~III~~ Initial Cond on Modal Coord

③

$$\underbrace{\{n\}}_{n(0)} = [\Phi]^{-1} \underbrace{\{x\}}_{x(0)} = [\Phi]^T [M] \underbrace{\{x\}}_{x(0)}$$